

# Representing Vectors Key Concepts

## Representing Vectors Lesson

### Component Form

The component form of a vector with initial point  $P(p_1, p_2)$  and terminal point  $Q(q_1, q_2)$  is given by  $\mathbf{v} = \langle q_1 - p_1, q_2 - p_2 \rangle = \langle v_1, v_2 \rangle$  where  $v_1$  is the horizontal component and  $v_2$  is the vertical component.

The magnitude (or length) of  $\mathbf{v}$  is given by

$$\|\mathbf{v}\| = \sqrt{(q_1 - p_1)^2 + (q_2 - p_2)^2} = \sqrt{(v_1)^2 + (v_2)^2}.$$

### Equal Vectors

Two vectors are equal if the two vectors have the same magnitude and direction. Let  $\mathbf{v} = \langle a, b \rangle$  and  $\mathbf{w} = \langle c, d \rangle$ ;  $\mathbf{v} = \mathbf{w}$  if and only if  $a = c$  and  $b = d$ .

## Operations with Vectors Lesson

### Vector Addition and Subtraction

If  $\mathbf{v} = \langle a, b \rangle$  and  $\mathbf{w} = \langle c, d \rangle$ , then  $\mathbf{v} \pm \mathbf{w} = \langle a, b \rangle \pm \langle c, d \rangle = \langle a \pm c, b \pm d \rangle$ .

### Scalar Multiplication

If  $\mathbf{v} = \langle a, b \rangle$  and  $k$  is a real number, then  $k\mathbf{v} = k\langle a, b \rangle = \langle ka, kb \rangle$  with a magnitude of  $|k|\|\mathbf{v}\|$ .

If  $k > 0$ , then the direction of  $k\mathbf{v}$  is the same as the direction of  $\mathbf{v}$ , and if  $k < 0$ , then the direction of  $k\mathbf{v}$  is the opposite of the direction of  $\mathbf{v}$ .

## Unit Vectors Lesson

### Writing Vectors as a Linear Combination of $\mathbf{i}$ and $\mathbf{j}$

If vector  $\mathbf{v} = \langle v_1, v_2 \rangle$ , then  $\mathbf{v} = v_1\mathbf{i} + v_2\mathbf{j}$  where  $v_1$  and  $v_2$  are the horizontal and vertical components of  $\mathbf{v}$ , respectively.

If vector  $\mathbf{v}$  has initial point  $P = (x_1, y_1)$  and terminal point  $Q = (x_2, y_2)$ , then  $\mathbf{v} = (x_2 - x_1)\mathbf{i} + (y_2 - y_1)\mathbf{j}$ .

### Operations with Vectors in Terms of $\mathbf{i}$ and $\mathbf{j}$

If  $\mathbf{v} = a_1\mathbf{i} + b_1\mathbf{j}$ ,  $\mathbf{w} = a_2\mathbf{i} + b_2\mathbf{j}$ , and  $k$  is a real number, then

$$\mathbf{v} + \mathbf{w} = (a_1 + a_2)\mathbf{i} + (b_1 + b_2)\mathbf{j}$$

$$\mathbf{v} - \mathbf{w} = (a_1 - a_2)\mathbf{i} + (b_1 - b_2)\mathbf{j}, \text{ and}$$

$$k\mathbf{v} = (ka_1)\mathbf{i} + (kb_1)\mathbf{j}$$

### Finding a Unit Vector

The vector  $\mathbf{u}$  is a scalar multiple of the vector  $\mathbf{v}$ . The vector  $\mathbf{u}$  has a magnitude of 1 and the same direction as  $\mathbf{v}$ . The vector  $\mathbf{u}$  is called a unit vector in the direction of  $\mathbf{v}$ .

$$\mathbf{u} = \frac{\mathbf{v}}{\|\mathbf{v}\|}$$

## Direction Angle Lesson

### Find the Direction Angle

Let  $\theta$  be the direction angle and  $\alpha$  be the reference angle. Find  $\theta$  by finding the tangent of the reference angle,  $\alpha$ .

$$\tan \alpha = \left| \frac{v_2}{v_1} \right|$$

When  $\theta$  lies in quadrant I,  $\theta = \alpha$ .

When  $\theta$  lies in quadrant II,  $\theta = 180 - \alpha$ .

When  $\theta$  lies in quadrant III,  $\theta = 180 + \alpha$ .

When  $\theta$  lies in quadrant IV,  $\theta = 360 - \alpha$ .

## Writing Vectors in Terms of Magnitude and Direction

A vector  $\mathbf{v} = a\mathbf{i} + b\mathbf{j}$  or  $\langle a, b \rangle$  may be represented by its magnitude and direction as

$$\mathbf{v} = \|\mathbf{v}\|\cos\theta\mathbf{i} + \|\mathbf{v}\|\sin\theta\mathbf{j} \text{ or}$$

$$\mathbf{v} = \langle \|\mathbf{v}\|\cos\theta, \|\mathbf{v}\|\sin\theta \rangle,$$

where  $\theta$  is the direction angle that measures the direction of the vector from the positive x-axis to  $\mathbf{v}$ .

## Dot Product Lesson

### Dot Product

If  $\mathbf{u} = \langle a_1, b_1 \rangle$  and  $\mathbf{v} = \langle a_2, b_2 \rangle$ , then the dot product, also called a scalar product, is denoted  $\mathbf{u} \cdot \mathbf{v}$ .

$$\mathbf{u} \cdot \mathbf{v} = a_1a_2 + b_1b_2$$

The product  $\mathbf{u} \cdot \mathbf{v}$  is a scalar, or real number. It is not a vector.

## Angle Between Two Vectors Lesson

### The Angle Between Two Vectors

Given two vectors,  $\mathbf{u}$  and  $\mathbf{v}$ , and  $\theta$  as the angle between vectors  $\mathbf{u}$  and  $\mathbf{v}$ , then  $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\|\|\mathbf{v}\|\cos\theta$ .

Therefore, to find the angle  $\theta$  between two vectors  $\mathbf{u}$  and  $\mathbf{v}$ ,

$$\cos\theta = \frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\|\|\mathbf{v}\|}, \text{ so}$$

$$\theta = \cos^{-1}\left(\frac{\mathbf{u} \cdot \mathbf{v}}{\|\mathbf{u}\|\|\mathbf{v}\|}\right)$$

where the angle  $\theta$  is such that  $0 \leq \theta \leq \pi$  or  $0^\circ \leq \theta \leq 180^\circ$ .

### Orthogonal Vectors

Two vectors are orthogonal if the angle between them,  $\theta$ , is equal to  $90^\circ$ .

Since  $\mathbf{u} \cdot \mathbf{v} = \|\mathbf{u}\|\|\mathbf{v}\|\cos\theta$  and  $\cos 90^\circ = 0$ , then  $\mathbf{u} \cdot \mathbf{v} = 0$ . Therefore, if the dot product of two vectors is zero, then the two vectors are orthogonal.

## Work

The work done,  $W$ , on a force,  $\mathbf{F}$ , that moves an object from initial point  $P$  to terminal point  $Q$  can be calculated using the following formula:

$$W = \mathbf{F} \cdot \overrightarrow{PQ} = \|\mathbf{F}\| \|\overrightarrow{PQ}\| \cos \theta$$